



# On affine conic and disjunctive constraints in Mosek version 10

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**Erling D. Andersen**

(joint work with Sven Wiese)

MOSEK ApS,

Company WWW: <https://mosek.com>

[www.mosek.com](http://www.mosek.com)





Background

Outline

Conic optimization

Disjunctive constraints



## Section 1

### Background





- A software package for solving:
  - Linear and **conic** problems.
  - Convex quadratically constrained problems.
  - Also mixed-integer versions of the above.
- Current version: 9.3.
- Current beta version: 10.0.

## Section 2

### Outline





- Conic optimization
  - What is it?
  - Why?
  - New interface to specify conic constraints.
- Disjunctive constraints
  - What is it?
  - Why?
  - How to specify disjunctive constraints.



## Section 3

### Conic optimization





$$\begin{aligned} & \text{minimize} && \sum (c^k)^T x^k \\ & \text{subject to} && \sum_k A^k x^k = b, \\ & && x^k \in \mathcal{K}^k, \quad \forall k, \end{aligned}$$

where

- $c^k \in \mathbb{R}^{n^k}$ ,
- $A^k \in \mathbb{R}^{m \times n^k}$ ,
- $b \in \mathbb{R}^m$ ,
- $\mathcal{K}^k$  are convex cones.





## Comments:

- Wikipedia reference:  
[https://en.wikipedia.org/wiki/Convex\\_cone](https://en.wikipedia.org/wiki/Convex_cone).
- Cone types:
  - Linear.
  - Quadratic.
  - Semi-definite.
  - Power cone.
  - Exponential.
- Most convex optimization models can be formulated with the **5** convex cone types.
- Evidence: Lubin [1] shows all convex instances (333) in the benchmark library MINLPLIB2 is conic representable using the 5 cones.





Mosek version 9 optimizer API interface:

$$\begin{bmatrix} x_5 \\ x_6 \\ x_8 \end{bmatrix} \in \mathcal{K}^k$$

- Only vector of variables can belong to a cone.
- In principle general. (Use artificial variables to handle affine expressions).
- Cumbersome to use at least for some models. (One solution: Cvxpy or Fusion).
- Want to specify an affine expression belonging to a cone easily.

I.e.

$$F^k x + f^k \in \mathcal{K}^k + g^k$$

Challenge:

- How to build an interface for this type of constraint.
- That works in a low level language like C.
- Extensible to new cone types.
- Efficient i.e. low space and computational overhead.
- Why the  $g$ ? Reason reuse of affine expression:

$$2 \leq x + y + 1 \text{ and } x + y + 1 \leq 6.$$





Define

$$Fx + f$$

which is a store/dictionary of affine expressions.

Assumptions:

- $F$  is a sparse matrix and  $f$  is a dense vector.
- Affine expressions can be appended but never deleted. (Important assumption!)
- Variables ( $x$ ) can be appended and deleted.
- Affine expressions can be modified.

Hence

$$F^k x + f^k = F_{\mathcal{I},:} x + f_{\mathcal{I}}$$

where  $\mathcal{I}$  is an ordered list of indexes.

Hence,

- $F^k$  is not provided explicitly.
- Represented by a list of indexes into the affine expression store.





## Introduce

$\mathcal{D}$

which is a list of domains. A domain

- has a dimension  $d$ .
- has type e.g. the exponential cone type.
- has potentially some associated parameters e.g.  $\alpha$ 's for the power cone.
- can never be deleted.



An affine conic constraint consist of:

- An ordered list of affine expressions indexes.
- A domain index.
- A  $g$  vector.

and represents

$$F_{\mathcal{I}};x + f_{\mathcal{I}} \in \mathcal{D}_k + g.$$

Comments:

- Conic constraints can be appended, deleted and modified.
- Dimension checking is simple.
- Everything is (easily) implementable in C.
- Extensible with new cone types. (Introduce new domains.)
- Can be implemented efficiently.

## Section 4

### Disjunctive constraints







A disjunctive constraint is of the form

$$[D^1x = b^1] \vee [D^2x = b^2] \vee \dots \vee [D^lx = b^l].$$

where

- $D^k \in \mathbb{R}^{m^k \times n}$ ,
- $b^k \in \mathbb{R}^{m^k}$ .

- Inequalities are fine.

- Wiki reference:

[https://optimization.mccormick.northwestern.edu/index.php/Disjunctive\\_inequalities](https://optimization.mccormick.northwestern.edu/index.php/Disjunctive_inequalities).



- Simple OR conditions: two jobs  $i, j$  with start times  $s_i, s_j$  have to be executed on the same machine, but only one at a time. So which one first?

$$[s_j \geq s_i + \textit{duration}_i] \vee [s_i \geq s_j + \textit{duration}_j].$$

- Semi-continuous variables:  $[x = 0] \vee [l \leq x \leq u]$ .
- An indicator constraint  $z = 1 \implies [d^T x \leq b]$  is the same as

$$[z = 0] \vee [d^T x \leq b].$$

Mosek's new `.mps` and `.lp` readers translate indicator constraints directly to disjunctions.



- Only one among some variables maybe non-zero, i.e.,  
SOS1( $x_1, \dots, x_k$ ):

$$[y_i = 1] \vee [x_i = 0], y_i \in \{0, 1\} \forall i, \sum_i y_i \leq 1.$$

- Complementarity constraints:  $s \cdot t = 0 \iff [s = 0] \vee [t = 0]$ .
- Piecewise linear functions:

$$[f = x, 0 \leq x \leq 1] \vee [f = 1 - 2x, 1 \leq x \leq 2] \vee [f = -3, 2 \leq x].$$

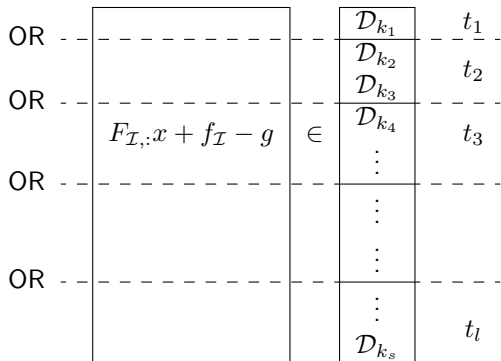


- Often disjunctive constraints can be reformulated with the big-M principle to ordinary Mixed-integer models (and Mosek may do this automatically!).
- For example the indicator constraint:  $d^T x \leq b + M(1 - z)$ .
- In some cases though, when (a valid)  $M$  is large or even infinite, this can lead to a certain loss in solution accuracy.



A disjunctive constraint in Mosek 10 consists of:

- An ordered list of affine expression indexes.
- An ordered list of domain indexes (only linear ones for now!).
- A  $g$  vector.
- A list of term sizes  $t_1, \dots, t_l$ :





- Described how to specify general affine conic constraints v10.
  - Efficient yet quite general when implemented in C.
  - Easy to extend to new cone types.
- Described how to specify disjunctive constraints in v10.
  - Generalize many special constructs such as semi-continuous variables, indicator constraints, SOS1 constraints etc.
  - Make it possible to get rid of big-Ms.
  - For now mainly syntactic sugar.



- [1] M. Lubin and E. Yamangil and R. Bent and J. P. Vielma. Extended Formulations in Mixed-integer Convex Programming. In Q. Louveaux and M. Skutella, editors, *Integer Programming and Combinatorial Optimization. IPCO 2016. Lecture Notes in Computer Science, Volume 9682*, pages 102–113. Springer, Cham, 2016.